$e^{-\frac{1}{2}\left(v_{s\rho 0}\frac{k_\rho}{\alpha_{s\rho 0}}\right)^2} e^{-j\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}\left(v_{s\rho 0}k_\rho\right)} e^{-\frac{1}{2}\left(v_{sz0}\frac{k_z}{\alpha_{sz0}}\right)^2} e^{-j\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}\left(v_{sz0}k_z\right)}$ that established the correct order to form the ordered "string" given in SUB-APPENDIX IV--Ordering of Associations: Matrix Method. The index over s is independent of m since each "FC" of a given "SFCs" is filtered by the same Gaussian filter. In embodiments, the index for the Gaussian filter is not independent of m. In one case, some "FCs" may be filtered by the same Gaussian filters; whereas, other "FCs" may be filtered by different Gaussian filters. In another case, each "FC" may be filtered by a different Gaussian filter.

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For the case where $v_{s,m}t_{0_{s,m}} = \rho_{0_{s,m}}$ and $k_\rho = k_z$., the "string" in Fourier space is one dimensional in terms of k_ρ and is given by

$$V_{\sum_{s,m}}\left(k_\rho, k_z\right) = \sum_{s=1}^{S}\sum_{m=1}^{M_s}\sum_{n=-\infty}^{\infty} a_{0_{s,m}} N_{s,m_{\rho 0}} e^{-\frac{1}{2}\left(v_{s\rho 0}\frac{k_\rho}{\alpha_{s\rho 0}}\right)^2} e^{-j\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}\left(v_{s\rho 0}k_\rho\right)} e^{-jk_\rho \rho_{\beta_{s,m}}} \sin\left(\left(k_\rho - n\frac{2\pi}{\rho_{0_{s,m}}}\right)\frac{N_{s,m_{\rho 0}}\rho_{0_{s,m}}}{2}\right) \tag{37.115}$$

The "string" comprises a Fourier series, a linear sum of "FCs" each multiplied by its corresponding Gaussian filter modulation factor and modulation factor which encodes input context (Eqs. (37.114-37.115)). FIGURE 19 is a flow diagram of an exemplary hierarchical relationship of the signals in Fourier space comprising "FCs", "SFCs", "groups of SFCs", and a "string" in accordance with the present invention. Each "FC" is encoded by a "P element" or stored into and/or recalled from a "M element" as shown in FIGURE 18.- -

IN THE CLAIMS

Please replace claims 51, 83, 94, 95, 118, 137, 138, 142, 157, 193, 204, 205, 242, 244-247, 248, 252 and 267 with the following claims 51, 83, 94, 95, 118, 137, 138, 142, 157, 193, 204, 205, 242, 244-247, 248, 252 and 267:

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51. (Amended) A method for recognizing a pattern in information comprising data, the method comprising:

inputting data;

encoding data as parameters of a plurality of Fourier components in Fourier space;

adding at least two of said Fourier components together to form at least one Fourier series in Fourier space;

sampling at least one of said Fourier series in Fourier space with a filter to form a sampled Fourier series;

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modulating said sampled Fourier series in Fourier space with said filter to form a modulated Fourier series;

determining a spectral similarity between said modulated Fourier series and another Fourier series;

determining a probability expectation value based on said spectral similarity;

generating a probability operand based on said probability expectation value;

selecting a desired value for said probability operand, wherein recognition of a pattern in said information is obtained when said probability operand having said desired value; and

outputting a recognized pattern.

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83. (Amended) A method according to claim 79, wherein each Fourier series of the string is multiplied by the Fourier transform of the delayed Gaussian filter represented by $e^{-\frac{1}{2}\left(v_{s\rho 0}\frac{k_\rho}{\alpha_{s\rho 0}}\right)^2} e^{-j\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}(v_{s\rho 0}k_\rho)} e^{-\frac{1}{2}\left(v_{sz0}\frac{k_z}{\alpha_{sz0}}\right)^2} e^{-j\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}(v_{sz0}k_z)}$ wherein the filter established the association to form the string, wherein the string is represented by:

$$\sum_{s=1}^{S}\sum_{m=1}^{M_s}\sum_{n=-\infty}^{\infty}\frac{4\pi}{1+\frac{k_z^2}{k_\rho^2}} a_{0_{s,m}} N_{s,m_{\rho_0}} N_{s,m_{z_0}} e^{-\frac{1}{2}\left(v_{s\rho 0}\frac{k_\rho}{\alpha_{s\rho 0}}\right)^2} e^{-j\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}(v_{s\rho 0}k_\rho)} e^{-\frac{1}{2}\left(v_{sz0}\frac{k_z}{\alpha_{sz0}}\right)^2} e^{-j\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}(v_{sz0}k_z)}$$

$$e^{-jk_\rho\left(\rho_{fbs,m}+\rho_{ts,m}\right)}\sin\left(\left(k_\rho - n\frac{2\pi}{\rho_{0_{s,m}}}\right)\frac{N_{s,m_{\rho_0}}\rho_{0_{s,m}}}{2}\right)\sin\left(\left(k_z - n\frac{2\pi}{v_{s,m}t_{0_{s,m}}}\right)\frac{N_{s,m_{z_0}}z_{0_{s,m}}}{2}\right)$$

wherein $v_{s\rho 0}$ and v_{sz0} are constants such as the signal propagation velocities in the ρ and z directions, respectively, $\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}$ and $\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}$ are delay parameters and $\alpha_{s\rho 0}$ and α_{sz0} are half-width parameters of a corresponding Gaussian filter in the ρ and z directions, respectively, $\rho_{t_{s,m}} = v_{t_{s,m}} t_{t_{s,m}}$ is the modulation factor which corresponds to the physical

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time delay $t_{t_{s,m}}$, $\rho_{fb_{s,m}} = v_{fb_{s,m}} t_{fb_{s,m}}$ is the modulation factor which corresponds to the specific transducer time delay $t_{fb_{s,m}}$, $v_{t_{s,m}}$ and $v_{fb_{s,m}}$ are constants such as the signal propagation velocities, $a_{0_{s,m}}$ is a constant, k_ρ and k_z are the frequency variables, n, m, s, M_s, and S are integers, and $N_{s,m_{\rho_0}}$, $N_{s,m_{z_0}}$, $\rho_{0_{s,m}}$, and $z_{0_{s,m}}$ are data parameters.

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94. (Amended) A method according to claim 91, wherein the filter is characterized in time by:

$$\frac{\alpha}{\sqrt{2\pi}} e^{\frac{\left(t - \frac{\sqrt{N}}{\alpha}\right)^2}{\frac{2}{\alpha^2}}}$$

wherein $\frac{\sqrt{N}}{\alpha}$ is a delay parameter, α is a half-width parameter, and t is the time parameter.

95. (Amended) A method according to claim 94, wherein the filter, in frequency space, is characterized by:

$$e^{-\frac{1}{2}\left(\frac{2\pi f}{\alpha}\right)^2} e^{-j\sqrt{N}\left(\frac{2\pi f}{\alpha}\right)}$$

wherein $\frac{\sqrt{N}}{\alpha}$ and α are a corresponding delay parameter and a half-width parameter in time, respectively, and f is the frequency parameter.

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118. (Amended) A method for recognizing a pattern in information, the method comprising:

inputting information;

representing the information as a plurality of Fourier series in Fourier space;

forming associations between at least two of the Fourier series by modulating and sampling the Fourier series with filters and by coupling the filtered Fourier series based on a probability distribution, wherein when at least two of the Fourier series have been associated recognition of a pattern in the information is achieved; and

outputting a recognized pattern in the information.

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137. (Amended) A method according to claim 127, wherein each filter of the set of filters is a time delayed Gaussian filter having a delay parameter $\frac{\sqrt{N}}{\alpha}$ which corresponds to a time point.

138. (Amended) A method according to claim 137, wherein each Fourier series of the string is multiplied by the Fourier transform of the delayed Gaussian filter represented by $e^{-\frac{1}{2}\left(v_{sp0}\frac{k_\rho}{\alpha_{sp0}}\right)^2} e^{-j\frac{\sqrt{N_{sp0}}}{\alpha_{sp0}}(v_{sp0}k_\rho)} e^{-\frac{1}{2}\left(v_{sz0}\frac{k_z}{\alpha_{sz0}}\right)^2} e^{-j\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}(v_{sz0}k_z)}$ wherein the filter established the correct order to form the string, wherein the ordered string is represented by:

$$\sum_{s=1}^{S}\sum_{m=1}^{M_s}\sum_{n=-\infty}^{\infty}\frac{4\pi}{1+\frac{k_z^2}{k_\rho^2}}a_{0_{s,m}}N_{s,m_{\rho_0}}N_{s,m_{z_0}}e^{-\frac{1}{2}\left(v_{sp0}\frac{k_\rho}{\alpha_{sp0}}\right)^2} e^{-j\frac{\sqrt{N_{sp0}}}{\alpha_{sp0}}(v_{sp0}k_\rho)} e^{-\frac{1}{2}\left(v_{sz0}\frac{k_z}{\alpha_{sz0}}\right)^2} e^{-j\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}(v_{sz0}k_z)}$$

$$e^{-jk_\rho\left(\rho_{fb_{s,m}}+\rho_{t_{s,m}}\right)}\sin\left(\left(k_\rho-n\frac{2\pi}{\rho_{0_{s,m}}}\right)\frac{N_{s,m_{\rho_0}}\rho_{0_{s,m}}}{2}\right)\sin\left(\left(k_z-n\frac{2\pi}{v_{s,m}t_{0_{s,m}}}\right)\frac{N_{s,m_{z_0}}z_{0_{s,m}}}{2}\right)$$

wherein v_{sp0} and v_{sz0} are constants such as the signal propagation velocities in the ρ and z directions, respectively, $\frac{\sqrt{N_{sp0}}}{\alpha_{sp0}}$ and $\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}$ are delay parameters and α_{sp0} and α_{sz0} are half-width parameters of a corresponding Gaussian filter in the ρ and z directions, respectively, $\rho_{t_{s,m}} = v_{t_{s,m}}t_{t_{s,m}}$ is the modulation factor which corresponds to the physical time delay $t_{t_{s,m}}$, $\rho_{fb_{s,m}} = v_{fb_{s,m}}t_{fb_{s,m}}$ is the modulation factor which corresponds to the specific transducer time delay $t_{fb_{s,m}}$, $v_{t_{s,m}}$ and $v_{fb_{s,m}}$ are constants such as the signal propagation velocities, $a_{0_{s,m}}$ is a constant, k_ρ and k_z are the frequency variables, n, m, s, M_s, and S are integers, and $N_{s,m_{\rho_0}}$, $N_{s,m_{z_0}}$, $\rho_{0_{s,m}}$, and $z_{0_{s,m}}$ are data parameters.

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142. (Amended) A method according to claim 138, wherein $v_{s,m}t_{0_{s,m}} = \rho_{0_{s,m}}$ and $k_\rho = k_z$ such that the string in Fourier space is one dimensional in terms of k_ρ and is represented by

$$\sum_{s=1}^{S}\sum_{m=1}^{M_s}\sum_{n=-\infty}^{\infty}a_{0_{s,m}}N_{s,m_{\rho_0}}e^{-\frac{1}{2}\left(v_{sp0}\frac{k_\rho}{\alpha_{sp0}}\right)^2} e^{-j\frac{\sqrt{N_{sp0}}}{\alpha_{sp0}}(v_{sp0}k_\rho)} e^{-jk_\rho\rho_{fb_{s,m}}}\sin\left(\left(k_\rho-n\frac{2\pi}{\rho_{0_{s,m}}}\right)\frac{N_{s,m_{\rho_0}}\rho_{0_{s,m}}}{2}\right)$$

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wherein $v_{s\rho 0}$ is a constant such as the signal propagation velocity in the ρ direction, $\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}$ is a delay parameter and $\alpha_{s\rho 0}$ is a half-width parameter of a corresponding Gaussian filter in the k_ρ-space, $\rho_{fbs,m} = v_{fbs,m} t_{fbs,m}$ is the modulation factor which corresponds to the specific transducer time delay $t_{fbs,m}$, $v_{fbs,m}$ is a constant such as the signal propagation velocity, $a_{0_{s,m}}$ is a constant, k_ρ is the frequency variable, n, m, s, M_s, and S are integers, and $N_{s,m_{\rho 0}}$ and $\rho_{0_{s,m}}$ are data parameters.

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193. (Amended) A computer-readable medium according to claim 189, wherein each Fourier series of the string is multiplied by the Fourier transform of the delayed Gaussian filter represented by $e^{-\frac{1}{2}\left(v_{s\rho 0}\frac{k_\rho}{\alpha_{s\rho 0}}\right)^2} e^{-j\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}(v_{s\rho 0}k_\rho)} e^{-\frac{1}{2}\left(v_{sz0}\frac{k_z}{\alpha_{sz0}}\right)^2} e^{-j\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}(v_{sz0}k_z)}$ wherein the filter established the association to form the string, wherein the string is represented by:

$$\sum_{s=1}^{S}\sum_{m=1}^{M_s}\sum_{n=-\infty}^{\infty}\frac{4\pi}{1+\frac{k_z^2}{k_\rho^2}} a_{0_{s,m}} N_{s,m_{\rho 0}} N_{s,m_{z0}} e^{-\frac{1}{2}\left(v_{s\rho 0}\frac{k_\rho}{\alpha_{s\rho 0}}\right)^2} e^{-j\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}(v_{s\rho 0}k_\rho)} e^{-\frac{1}{2}\left(v_{sz0}\frac{k_z}{\alpha_{sz0}}\right)^2} e^{-j\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}(v_{sz0}k_z)}$$

$$e^{-jk_\rho\left(\rho_{fbs,m}+\rho_{ts,m}\right)} \sin\left(\left(k_\rho - n\frac{2\pi}{\rho_{0_{s,m}}}\right)\frac{N_{s,m_{\rho 0}}\rho_{0_{s,m}}}{2}\right) \sin\left(\left(k_z - n\frac{2\pi}{v_{s,m}t_{0_{s,m}}}\right)\frac{N_{s,m_{z0}}z_{0_{s,m}}}{2}\right)$$

wherein $v_{s\rho 0}$ and v_{sz0} are constants such as the signal propagation velocities in the ρ and z directions, respectively, $\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}$ and $\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}$ are delay parameters and $\alpha_{s\rho 0}$ and α_{sz0} are half-width parameters of a corresponding Gaussian filter in the ρ and z directions, respectively, $\rho_{t_{s,m}} = v_{t_{s,m}} t_{t_{s,m}}$ is the modulation factor which corresponds to the physical time delay $t_{t_{s,m}}$, $\rho_{fbs,m} = v_{fbs,m} t_{fbs,m}$ is the modulation factor which corresponds to the specific transducer time delay $t_{fbs,m}$, $v_{t_{s,m}}$ and $v_{fbs,m}$ are constants such as the signal propagation velocities, $a_{0_{s,m}}$ is a constant, k_ρ and k_z are the frequency variables, n, m, s, M_s, and S are integers, and $N_{s,m_{\rho 0}}$, $N_{s,m_{z0}}$, $\rho_{0_{s,m}}$, and $z_{0_{s,m}}$ are data parameters

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204. (Amended) A computer-readable medium according to claim 201, wherein the filter is characterized in time by:

$$\frac{\alpha}{\sqrt{2\pi}} e^{\frac{\left(t-\frac{\sqrt{N}}{\alpha}\right)^2}{\frac{2}{\alpha^2}}}$$

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wherein $\frac{\sqrt{N}}{\alpha}$ is a delay parameter, α is a half-width parameter, and t is the time parameter.

205. (Amended) A computer-readable medium according to claim 201, wherein the filter, in frequency space, is characterized by:

$$e^{-\frac{1}{2}\left(\frac{2\pi f}{\alpha}\right)^2} e^{-j\sqrt{N}\left(\frac{2\pi f}{\alpha}\right)}$$

wherein $\frac{\sqrt{N}}{\alpha}$ and α are a corresponding delay parameter and a half-width parameter in time, respectively, and f is the frequency parameter.

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242. (Amended) A computer-readable medium according to claim 237, wherein said probability operands having a value selected from a set of zero and one.

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244. (Amended) A computer-readable medium to claim 237, wherein the high level memory is initialized with standard inputs.

245. (Amended) A computer-readable medium to claim 237, wherein the ordering is according to one of the list of: temporal order, cause and effect relationships, size order, intensity order, before-after order, top-bottom order, or left-right order.

246. (Amended) A computer-readable medium to claim 237, wherein each filter of the set of filters is a time delayed Gaussian filter having a half-width parameter α which determines the amount of the string that is sampled.

247. (Amended) A computer-readable medium to claim 237, wherein each filter of the set of filters is a time delayed Gaussian filter having a delay parameter $\frac{\sqrt{N}}{\alpha}$ which corresponds to a time point.

248. (Amended) A computer-readable medium to claim 247, wherein each Fourier series of the string is multiplied by the Fourier transform of the delayed Gaussian filter

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represented by $e^{-\frac{1}{2}\left(v_{s\rho 0}\frac{k_\rho}{\alpha_{s\rho 0}}\right)^2} e^{-j\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}(v_{s\rho 0}k_\rho)} e^{-\frac{1}{2}\left(v_{sz0}\frac{k_z}{\alpha_{sz0}}\right)^2} e^{-j\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}(v_{sz0}k_z)}$ wherein the filter established the correct order to form the string, wherein the ordered string is represented by:

$$\sum_{s=1}^{S}\sum_{m=1}^{M_s}\sum_{n=-\infty}^{\infty}\frac{4\pi}{1+\frac{k_z^2}{k_\rho^2}} a_{0_{s,m}} N_{s,m_{\rho 0}} N_{s,m_{z0}} e^{-\frac{1}{2}\left(v_{s\rho 0}\frac{k_\rho}{\alpha_{s\rho 0}}\right)^2} e^{-j\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}(v_{s\rho 0}k_\rho)} e^{-\frac{1}{2}\left(v_{sz0}\frac{k_z}{\alpha_{sz0}}\right)^2} e^{-j\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}(v_{sz0}k_z)}$$

$$e^{-jk_\rho\left(\rho_{fbs,m}+\rho_{ts,m}\right)} \sin\left(\left(k_\rho - n\frac{2\pi}{\rho_{0_{s,m}}}\right)\frac{N_{s,m_{\rho 0}}\rho_{0_{s,m}}}{2}\right)\sin\left(\left(k_z - n\frac{2\pi}{v_{s,m}t_{0_{s,m}}}\right)\frac{N_{s,m_{z0}}z_{0_{s,m}}}{2}\right)$$

wherein $v_{s\rho 0}$ and v_{sz0} are constants such as the signal propagation velocities in the ρ and z directions, respectively, $\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}$ and $\frac{\sqrt{N_{sz0}}}{\alpha_{sz0}}$ are delay parameters and $\alpha_{s\rho 0}$ and α_{sz0} are half-width parameters of a corresponding Gaussian filter in the ρ and z directions, respectively, $\rho_{t_{s,m}} = v_{t_{s,m}} t_{t_{s,m}}$ is the modulation factor which corresponds to the physical time delay $t_{t_{s,m}}$, $\rho_{fb_{s,m}} = v_{fb_{s,m}} t_{fb_{s,m}}$ is the modulation factor which corresponds to the specific transducer time delay $t_{fb_{s,m}}$, $v_{t_{s,m}}$ and $v_{fb_{s,m}}$ are constants such as the signal propagation velocities, $a_{0_{s,m}}$ is a constant, k_ρ and k_z are the frequency variables, n, m, s, M_s, and S are integers, and $N_{s,m_{\rho 0}}$, $N_{s,m_{z0}}$, $\rho_{0_{s,m}}$, and $z_{0_{s,m}}$ are data parameters.

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252. (Amended) A computer-readable medium to claim 248, wherein $v_{s,m}t_{0_{s,m}} = \rho_{0_{s,m}}$ and $k_\rho = k_z$ such that the string in Fourier space is one dimensional in terms of k_ρ and is represented by

$$\sum_{s=1}^{S}\sum_{m=1}^{M_s}\sum_{n=-\infty}^{\infty} a_{0_{s,m}} N_{s,m_{\rho 0}} e^{-\frac{1}{2}\left(v_{s\rho 0}\frac{k_\rho}{\alpha_{s\rho 0}}\right)^2} e^{-j\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}(v_{s\rho 0}k_\rho)} e^{-jk_\rho\rho_{fb_{s,m}}} \sin\left(\left(k_\rho - n\frac{2\pi}{\rho_{0_{s,m}}}\right)\frac{N_{s,m_{\rho 0}}\rho_{0_{s,m}}}{2}\right)$$

wherein $v_{s\rho 0}$ is a constant such as the signal propagation velocity in the ρ direction, $\frac{\sqrt{N_{s\rho 0}}}{\alpha_{s\rho 0}}$ is a delay parameter and $\alpha_{s\rho 0}$ is a half-width parameter of a corresponding Gaussian filter in the k_ρ-space, $\rho_{fb_{s,m}} = v_{fb_{s,m}} t_{fb_{s,m}}$ is the modulation factor which corresponds to the specific transducer time delay $t_{fb_{s,m}}$, $v_{fb_{s,m}}$ is a constant such as the signal propagation velocity, $a_{0_{s,m}}$ is a constant, k_ρ is the frequency variable, n, m, s, M_s, and S are integers, and $N_{s,m_{\rho 0}}$ and $\rho_{0_{s,m}}$ are data parameters.
